

# Closure concept for 2-factors in claw-free graphs

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## Abstract

We introduce a closure concept for 2-factors in claw-free graphs that generalizes the closure introduced by the first author. The 2-factor closure of a graph is uniquely determined and the closure operation turns a claw-free graph into the line graph of a graph containing no cycles of length at most 5 and no cycles of length 6 satisfying a certain condition. A graph has a 2-factor if and only if its closure has a 2-factor; however, the closure operation preserves neither the minimum number of components of a 2-factor nor the hamiltonicity or nonhamiltonicity of a graph.

**Keywords:** closure; 2-factor; claw-free graph; line graph; dominating system.

## 1 Introduction

By a *graph* we always mean a simple loopless finite undirected graph  $G = (V(G), E(G))$ . We use standard graph-theoretical notation and terminology and for concepts and notations not defined here we refer the reader to [1].

The degree of a vertex  $x \in V(G)$  is denoted  $d_G(x)$ , and  $\delta(G)$  denotes the *minimum degree* of  $G$ , i.e.  $\delta(G) = \min\{d_G(x) \mid x \in V(G)\}$ . An edge of  $G$  is a *pendant edge* if some of its vertices is of degree 1. The *distance in  $G$*  of two vertices  $x, y \in V(G)$  is denoted  $\text{dist}_G(x, y)$ , and for two subgraphs  $F_1, F_2 \subset G$  we denote  $\text{dist}_G(F_1, F_2) = \min\{\text{dist}_G(x, y) \mid x \in V(F_1), y \in V(F_2)\}$ . If  $F$  is a subgraph of  $G$ , we simply write  $G - F$  for  $G - V(F)$ .

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For a set of vertices  $S \subset V(G)$ ,  $\langle S \rangle_G$  denotes the subgraph *induced* by  $S$ , and for a set of edges  $D \subset E(G)$ ,  $\langle\langle D \rangle\rangle_G$  denotes the *edge-induced subgraph* determined by the set  $D$ . A *clique* is a (not necessarily maximal) complete subgraph of a graph  $G$ , and, for an edge  $e \in E(G)$ ,  $\omega_G(e)$  denotes the largest order of a clique containing  $e$ .

A cycle of length  $i$  is denoted  $C_i$ , and for a cycle  $C$  with a given orientation and a vertex  $x \in V(C)$ ,  $x^-$  and  $x^+$  denotes the predecessor and successor of  $x$  on  $C$ , respectively.

The *girth* of a graph  $G$ , denoted  $g(G)$ , is the length of a shortest cycle in  $G$ , and the *circumference* of  $G$ , denoted  $c(G)$ , is the length of a longest cycle in  $G$ . A cycle (path) in  $G$  having  $|V(G)|$  vertices is called a *hamiltonian cycle* (*hamiltonian path*), and a graph containing a hamiltonian cycle (hamiltonian path) is said to be *hamiltonian* (*traceable*), respectively. A *2-factor* in a graph  $G$  is a spanning subgraph of  $G$  in which all vertices have degree 2. Thus, a hamiltonian cycle is a connected 2-factor.

If  $H$  is a graph, then the *line graph* of  $H$ , denoted  $L(H)$ , is the graph with  $E(H)$  as vertex set, in which two vertices are adjacent if and only if the corresponding edges have a vertex in common. It is well-known that if  $G$  is a line graph (of some graph), then the graph  $H$  such that  $G = L(H)$  is uniquely determined (with one exception of the graphs  $C_3$  and  $K_{1,3}$ , for which both  $L(C_3)$  and  $L(K_{1,3})$  are isomorphic to  $C_3$ ). The graph  $H$  for which  $L(H) = G$  will be called the *preimage* of  $G$  and denoted  $H = L^{-1}(G)$ .

Let  $H$  be a graph and  $e = xy \in E(H)$  an edge of  $H$ . Let  $H|_e$  be the graph obtained from  $H$  by identifying  $x$  and  $y$  to a new vertex  $v_e$  and adding to  $v_e$  a (new) pendant edge  $e'$ . Then we say that  $H|_e$  is obtained from  $H$  by *contraction* of the edge  $e$ . Note that  $|E(H)| = |E(H|_e)|$ .

The *neighborhood* of a vertex  $x \in V(G)$  is the set  $N_G(x) = \{y \in V(G) \mid xy \in E(G)\}$ , and for  $S \subset V(G)$  we denote  $N_G(S) = \cup_{x \in S} N_G(x)$ . For a vertex  $x \in V(G)$ , the graph  $G_x^*$  with  $V(G_x^*) = V(G)$  and  $E(G_x^*) = E(G) \cup \{uv \mid u, v \in N_G(x)\}$  is called the *local completion of  $G$  at  $x$* .

The following proposition, which is easy to observe (see also [9]), shows the relation between the operations of local completion and of contraction of an edge.

**Proposition A.** *Let  $H$  be a graph,  $e \in E(H)$ ,  $G = L(H)$ , and let  $x \in V(G)$  be the vertex corresponding to the edge  $e$ . Then  $G_x^* = L(H|_e)$ .*

Note that if  $e$  is in a triangle then  $H|_e$  may contain a multiple edge. To avoid necessity of working with multigraphs in this paper, we will always arrange local completions in such a way that Proposition A is always applied to a triangle-free graph.

We say that a graph is *even* if every its vertex has positive even degree. A connected even graph is called a *circuit*, and the complete bipartite graph  $K_{1,m}$  is a *star*. Specifically, the four-vertex star  $K_{1,3}$  will be referred to as the *claw*. A subgraph  $F$  of a graph  $H$  *dominates*  $H$  if  $F$  dominates every edge of  $H$ , i.e. if every edge of  $H$  has at least one vertex in  $V(F)$ . Let  $\mathcal{S}$  be a set of edge-disjoint circuits and stars with at least three edges in  $H$ . We say that  $\mathcal{S}$  is a *dominating system* (abbreviated *d-system*) in  $H$  if every edge of  $H$  that is not in a star of  $\mathcal{S}$  is dominated by a circuit in  $\mathcal{S}$ . We will use the following result by Gould and Hynds [5].

**Theorem B [5].** *Let  $H$  be a graph. Then  $L(H)$  has a 2-factor with  $c$  components if and only if  $H$  has a  $d$ -system with  $c$  elements.*

A graph  $G$  is said to be *claw-free* if  $G$  does not contain an induced subgraph isomorphic to the claw  $K_{1,3}$ . It is a well-known fact that every line graph is claw-free, hence the class of claw-free graphs can be considered as a natural generalization of the class of line graphs. For more information on claw-free graphs, see e.g. the survey paper [4].

In the class of claw-free graphs, a closure concept has been introduced in [8] as follows. Let  $G$  be a claw-free graph and  $x \in V(G)$ . We say that  $x$  is *locally connected* if  $\langle N_G(x) \rangle_G$  is a connected graph,  $x$  is *simplicial* if  $\langle N_G(x) \rangle_G$  is a clique, and  $x$  is *eligible* if  $x$  is locally connected and nonsimplicial. The set of eligible or simplicial vertices of a graph  $G$  is denoted  $\text{EL}(G)$  or  $\text{SI}(G)$ , respectively. The graph, obtained from  $G$  by recursively performing the local completion operation at eligible vertices, as long as this is possible, is called the *closure* of  $G$  and denoted  $\text{cl}(G)$ . (More precisely: there are graphs  $G_1, \dots, G_k$  such that  $G_1 = G$ ,  $G_{i+1} = (G_i)_{x_i}^*$  for some  $x_i \in \text{EL}(G_i)$ ,  $i = 1, \dots, k-1$ ,  $G_k = \text{cl}(G)$  and  $\text{EL}(G_k) = \emptyset$ .)

The following result summarizes basic properties of the closure.

**Theorem C [8].** *For every claw-free graph  $G$ :*

- (i)  $\text{cl}(G)$  is uniquely determined,
- (ii)  $\text{cl}(G)$  is the line graph of a triangle-free graph,
- (iii)  $c(\text{cl}(G)) = c(G)$ ,
- (iv)  $\text{cl}(G)$  is hamiltonian if and only if  $G$  is hamiltonian.

In [10] it was shown that the closure operation preserves also the existence or nonexistence of a 2-factor. More specifically, the following was proved in [10].

**Theorem D [10].** *Let  $G$  be a claw-free graph and let  $x \in \text{EL}(G)$ . If  $G_x^*$  has a 2-factor with  $k$  components, then  $G$  has a 2-factor with at most  $k$  components.*

Consequently, the local completion operation performed at eligible vertices preserves the minimum number of components of a 2-factor. Specifically, we obtain the following.

**Corollary E [10].** *Let  $G$  be a claw-free graph. Then  $G$  has a 2-factor if and only if  $\text{cl}(G)$  has a 2-factor.*

Further properties of  $\text{cl}(G)$  are summarized in the survey paper [3].

In this paper, we significantly strengthen the closure concept such that it still preserves the (non)-existence of a 2-factor.

## 2 Closure concept

Let  $C_k$  be a cycle of even length  $k \geq 4$ . Two edges  $e_1, e_2 \in E(G)$  are said to be *antipodal in  $C_k$* , if they are at maximum distance in  $C_k$  (i.e.,  $\text{dist}_{C_k}(e_1, e_2) = k/2 - 1$ ). An even cycle  $C_k$  in a graph  $G$  is said to be *edge-antipodal*, abbreviated EA, if  $\min\{\omega_G(e_1), \omega_G(e_2)\} = 2$  for any two antipodal edges  $e_1, e_2 \in E(C_k)$ . Analogously, two vertices  $x_1, x_2 \in V(C_k)$  are *antipodal in  $C_k$*  if they are at maximum distance in  $C_k$  (i.e.  $\text{dist}_{C_k}(x_1, x_2) = k/2$ ), and

$C_k$  is said to be *vertex-antipodal*, abbreviated VA, if  $\min\{d_G(x_1), d_G(x_2)\} = 2$  for any two antipodal vertices  $x_1, x_2 \in V(C_k)$ .

Let  $G$  be a claw-free graph. A vertex  $x \in V(G)$  is said to be *2f-eligible*, if  $x$  satisfies one of the following:

- (i)  $x \in \text{EL}(G)$ ,
- (ii)  $x \notin \text{EL}(G)$  and  $x$  is in an induced cycle of length 4 or 5 or in an induced EA-cycle of length 6.

The set of all 2f-eligible vertices of  $G$  will be denoted  $\text{EL}^{2f}(G)$ .

We say that a graph  $\text{cl}^{2f}(G)$  is a *2-factor-closure* (abbreviated 2f-closure) of a claw-free graph  $G$ , if there is a sequence of graphs  $G_1, \dots, G_k$  such that

- (i)  $G_1 = G$ ,
- (ii)  $G_{i+1} = (G_i)_{x_i}^*$  for some  $x_i \in \text{EL}^{2f}(G_i)$ ,  $i = 1, \dots, k-1$ ,
- (iii)  $G_k = \text{cl}^{2f}(G)$  and  $\text{EL}^{2f}(G_k) = \emptyset$ .

Thus, the 2f-closure of a claw-free graph  $G$  is obtained by recursively repeating the local completion operation at 2f-eligible vertices, as long as this is possible. In the next section we will show that, for a given claw-free graph  $G$ , its 2f-closure is uniquely determined, which will justify the notation  $\text{cl}^{2f}(G)$ .

The graph  $G$  in Figure 1 is an example of a claw-free graph with a complete 2f-closure, in which  $\text{EL}(G) = \emptyset$ . Note that  $G$  is nonhamiltonian and  $G - x$  is nontraceable, while  $\text{cl}^{2f}(G)$  is complete and  $\text{cl}^{2f}(G - x)$  is traceable. Hence  $\text{cl}^{2f}(G)$  preserves neither the (non)-hamiltonicity nor the (non)-traceability of a graph. Moreover, since  $G$  is nonhamiltonian and  $\text{cl}^{2f}(G)$  is complete, this example also shows that  $\text{cl}^{2f}(G)$  does not preserve the minimum number of components of a 2-factor, i.e., an analogue of Theorem D is not true for  $\text{cl}^{2f}(G)$ . However, in Section 4 we will prove the analogue of Corollary E for  $\text{cl}^{2f}(G)$ .

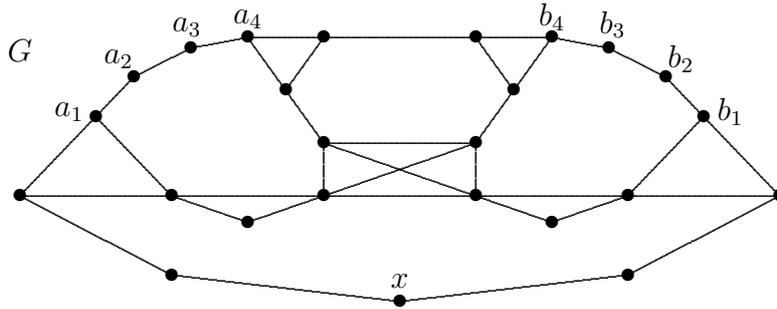


Figure 1

### 3 Uniqueness of the closure

We recall some definitions and facts from [6] that will be helpful to prove the uniqueness of  $\text{cl}^{2f}(G)$  as a special case of a more general setting.

Let  $\mathcal{C}$  be a class of graphs and let  $\mathcal{P}$  be a function on  $\mathcal{C}$  such that, for any  $G \in \mathcal{C}$ ,  $\mathcal{P}(G) \subset 2^{V(G)}$  (i.e.,  $\mathcal{P}(G)$  is a set of subsets of  $V(G)$ ). For any  $X \subset V(G)$  let  $G_X^*$  denote the local completion of  $G$  at  $X$ , i.e. the graph with  $V(G_X^*) = V(G)$  and  $E(G_X^*) = E(G) \cup \{uv \mid u, v \in X\}$  (thus, the previous notation  $G_x^*$  means that, for a vertex  $x \in V(G)$ , we simply write  $G_x^*$  for  $G_{N_G(x)}^*$ ).

We say that a graph  $F$  is a  $\mathcal{P}$ -extension of  $G$ , denoted  $G \preceq F$ , if there is a sequence of graphs  $G_0 = G, G_1, \dots, G_k = F$  such that  $G_{i+1} = (G_i)_{X_i}^*$  for some  $X_i \in \mathcal{P}(G_i)$ . Clearly, for any graph  $G$  there is a  $\preceq$ -maximal  $\mathcal{P}$ -extension  $H$ , and in this case we say that  $H$  is a  $\mathcal{P}$ -closure of  $G$ . If a  $\mathcal{P}$ -closure is uniquely determined then it is denoted by  $\text{cl}_{\mathcal{P}}(G)$ . Finally, a function  $\mathcal{P}$  is *non-decreasing* (on a class  $\mathcal{C}$ ), if, for any  $H, H' \in \mathcal{C}$ ,  $H \preceq H'$  implies that for any  $X \in \mathcal{P}(H)$  there is an  $X' \in \mathcal{P}(H')$  such that  $X \subset X'$ .

The following result was proved in [6]. For the sake of completeness, we include its (short) proof here.

**Theorem F [6].** *If  $\mathcal{P}$  is a non-decreasing function on a class  $\mathcal{C}$ , then, for any  $G \in \mathcal{C}$ , a  $\mathcal{P}$ -closure of  $G$  is uniquely determined.*

**Proof.** Let  $H \neq H'$  be  $\mathcal{P}$ -closures of  $G$ , let  $G = G_0, G_1, \dots, G_k = H'$  be such that  $G_{i+1} = (G_i)_{X_i}^*$  for some  $X_i \in \mathcal{P}(G_i)$ , and let  $s$  be a smallest integer such that  $G_s \not\subset H$ . Since  $G_{s-1} \subset H$  and  $\mathcal{P}$  is non-decreasing, there is  $X \in \mathcal{P}(H)$  such that  $X_{s-1} \subset X$ . Since  $H$  is  $\preceq$ -maximal, we have  $H_X^* = H$ , a contradiction. ■

It is easy to see that  $\mathcal{P}(G) = \{N_G(x) \mid x \in \text{EL}^{2f}(G) \cup \text{SI}(G)\}$  is a non-decreasing function on the class  $\mathcal{C}$  of claw-free graphs, and  $\text{cl}_{\mathcal{P}}(G)$  equals the 2f-closure of  $G$ . This immediately implies the following fact.

**Proposition 1.** *For any claw-free graph  $G$ , the 2f-closure of  $G$  is uniquely determined.* ■

## 4 Properties of the closure

The following result summarizes basic properties of the 2f-closure.

**Theorem 2.** *Let  $G$  be a claw-free graph. Then*

- (i) *the closure  $\text{cl}^{2f}(G)$  is uniquely determined,*
- (ii) *there is a graph  $H$  such that*
  - ( $\alpha$ )  $L(H) = \text{cl}^{2f}(G)$ ,
  - ( $\beta$ )  $g(H) \geq 6$ ,
  - ( $\gamma$ )  $H$  *does not contain any vertex-antipodal cycle of length 6,*
- (iii)  $G$  *has a 2-factor if and only if  $\text{cl}^{2f}(G)$  has a 2-factor.*

**Proof.** (i) Part (i) follows immediately from Proposition 1.

(ii) By (i), the 2f-closure does not depend on the order of 2f-eligible vertices used during the construction of  $\text{cl}^{2f}(G)$ . Thus, we can first apply local completion to eligible vertices, obtaining  $\text{cl}(G)$ , and then apply local completion to 2f-eligible vertices of  $\text{cl}(G)$ . In some steps, it is possible that again  $\text{EL}(G_i) \neq \emptyset$  and, if this occurs, we choose  $x_i$  such that  $x_i \in \text{EL}(G_i)$ , as long as this is possible. Let  $G_1, \dots, G_k$  be the resulting sequence of graphs and  $x_1, \dots, x_{k-1}$  the corresponding sequence of 2f-eligible vertices, i.e.  $G_1 = G$ ,  $G_k = \text{cl}^{2f}(G)$ ,  $G_{i+1} = (G_i)_{x_i}^*$  and  $x_i \in \text{EL}^{2f}(G_i)$ ,  $i = 1, \dots, k-1$ . Then, any time when  $x \in \text{EL}(G_i)$ , the subsequence of eligible vertices yields a triangle-free graph by Theorem C and thus, any time when  $x_i \in \text{EL}^{2f}(G_i) \setminus \text{EL}(G_i)$ , the choice of  $x_i$  guarantees that  $G_i = L(H_i)$  for some triangle-free graph  $H_i$ . Then, by Proposition A,  $G_{i+1} = (G_i)_{x_i}^* = L(H_i|_{e_i})$ , where  $e_i$  is the edge of  $H_i$  corresponding to the vertex  $x_i \in V(G_i)$ , and the fact that  $H_i$  is triangle-free guarantees that  $H_i|_{e_i}$  is a graph (i.e. the contraction of  $e_i$  does not create a multiple edge). By induction, each  $G_i$  is a line graph. Since  $L^{-1}(C_i) = C_i$ , and the preimage of an EA- $C_6$  is a VA- $C_6$ , the graph  $H = L^{-1}(\text{cl}^{2f}(G))$  has the required properties.

(iii) Clearly, every 2-factor in  $G$  is a 2-factor in  $\text{cl}^{2f}(G)$ , hence we need to prove that if  $\text{cl}^{2f}(G)$  has a 2-factor then  $G$  has a 2-factor.

Similarly as in part (ii) of the proof, we can construct  $\text{cl}^{2f}(G)$  such that we first apply local completion to eligible vertices as long as this is possible, and we obtain  $\overline{G} = \text{cl}(G)$  and the triangle-free graph  $\overline{H} = L^{-1}(\overline{G})$ . The 2f-closure of  $G$  is then obtained by applying local completion to 2f-eligible vertices. In the  $i$ -th step of the construction we then have  $G_{i+1} = (G_i)_{v_i}^*$ , where  $v_i \in \text{EL}^{2f}(G_i)$ . If  $v_i \in \text{EL}(G_i)$ , we are done by Theorem D, hence suppose that  $\text{EL}(G_i) = \emptyset$  and  $v_i$  is in an induced cycle  $C_G$ . By the definition of the 2f-closure,  $C_G$  is a  $C_4$ , a  $C_5$  or an EA- $C_6$ .

Let  $H = L^{-1}(G_i)$ ,  $C = L^{-1}(C_G)$ , and let  $e = xy \in E(H)$  be the edge corresponding to  $v_i$ . Then  $e \in E(C)$  and  $C$  is a  $C_4$ , a  $C_5$  or a VA- $C_6$ . We will suppose that  $C$  is oriented such that  $x = y^+$ . By Proposition A, we have  $L^{-1}((G_i)_{v_i}^*) = H|_e$ , thus, by Theorem B, it remains to prove the following claim.

**Claim 3.** *If  $H|_e$  has a  $d$ -system, then  $H$  has a  $d$ -system.*

We set  $H' = H|_e$  and denote by  $v_e$  the vertex obtained by contracting  $e = xy$ , and by  $e'$  the pendant edge (corresponding to  $e$ ) attached to  $v_e$ .

Let  $\mathcal{S}'$  be a  $d$ -system in  $H'$ , and let  $B(\mathcal{S}')$  and  $St(\mathcal{S}')$  be the set of circuits and the set of stars in  $\mathcal{S}'$ , respectively. Note that in the spanning subgraph (of  $H'$ )

$$D' = (V(H'), \bigcup_{B \in B(\mathcal{S}')} E(B)),$$

every vertex has even degree (possibly zero). We can suppose that there is no star in  $\mathcal{S}'$  whose center has positive even degree in  $D'$  because all the edges of such a star are dominated by the circuit passing through the center. Since  $e'$  is a pendant edge in  $H'$ ,  $e' \notin E(D')$ , hence there exists either a star in  $St(\mathcal{S}')$  whose center is  $v_e$ , or a circuit in  $B(\mathcal{S}')$  passing through  $v_e$ . If there is a star in  $St(\mathcal{S}')$  whose center is  $v_e$ , we denote this star by  $T'$ ; otherwise let  $T'$  be an empty graph, i.e.,  $V(T') = \emptyset$ . Let  $\mathcal{S}$  be the set of the subgraphs in  $H$  corresponding to the stars in  $St(\mathcal{S}') \setminus \{T'\}$  and  $D$  the spanning subgraph

in  $H$  corresponding to  $D'$ . Notice that all elements in  $S$  are stars in  $H$  and  $d_D(x) \equiv d_D(y) \pmod{2}$ .

Suppose first that both  $x$  and  $y$  have positive degree in  $D$ . Then there exists a circuit in  $B(\mathcal{S}')$  passing through  $v_e$ , and there is no star in  $St(\mathcal{S}')$  with center at  $v_e$ . If both  $x$  and  $y$  have positive even degree in  $D$ , then  $D$  and  $S$  determine a d-system in  $H$  since the edge  $e$  is dominated in  $H$  by any of the circuits passing through  $x$  and  $y$ . Similarly, if both  $x$  and  $y$  have positive odd degree, then  $D + e$  and  $S$  determine a d-system in  $H$ .

Hence we suppose that  $d_D(x) = 0$  or  $d_D(y) = 0$ . By symmetry, let  $d_D(y) = 0$ . If  $C - \langle\langle E(D) \cap E(C) \rangle\rangle_H$  is edgeless (i.e., all edges of  $C$  have at least one vertex with positive degree in  $D$ ), then  $d_D(x) \geq 2$  and  $d_D(y^-) \geq 2$ . If  $T'$  has no edge whose corresponding edge in  $H$  is incident to  $y$ , then  $D$  and  $S$  determine a d-system of  $H$  since the edges  $e = xy$  and  $yy^-$  are dominated by the circuits in  $D$  passing through  $x$  and  $y^-$ , respectively. If  $T'$  has an edge whose corresponding edge in  $H$  is incident to  $y$ , then  $D$  and the set of stars which obtained by adding to  $S$  the star consisting of  $xy$ ,  $yy^-$  and all the corresponding edges incident to  $y$ , determine a d-system in  $H$ . Note that in the last case (i.e. if we added a star), the number of elements of the d-system under consideration is increased (and in this case also the minimum number of components of a 2-factor can be increased).

Therefore we suppose  $C - \langle\langle E(D) \cap E(C) \rangle\rangle_H$  contains an edge. This implies

$$|E(D) \cap E(C)| \leq |E(C)| - 3. \quad (1)$$

Let  $\tilde{D} = \langle\langle (E(D) \cup E(C)) \setminus (E(D) \cap E(C)) \rangle\rangle_H$ . As in the above, we can construct a d-system in  $H$  if  $C - \langle\langle E(\tilde{D}) \cap E(C) \rangle\rangle_H$  is edgeless. Indeed, in this case  $d_{\tilde{D}}(x) \geq 2$  and  $d_{\tilde{D}}(y) \geq 2$  since  $e \in E(\tilde{D})$ . Therefore neither  $x$  nor  $y$  are singletons in  $\tilde{D}$ . If there is a vertex  $x_i \in C - \langle\langle E(\tilde{D}) \cap E(C) \rangle\rangle_H$  such that some edges incident to  $x_i$  have no vertex in  $\tilde{D}$ , then we construct a star from all such edges and the edges  $x_i^-x_i$ ,  $x_ix_i^+$ . Let  $S_1$  be the set of all such stars for vertices in  $C - \langle\langle E(\tilde{D}) \cap E(C) \rangle\rangle_H$  and  $S_2$  the set of all stars in  $S$  whose centers are on  $C$ . Then  $\tilde{D}$  and  $(S \setminus S_2) \cup S_1$  determine a d-system in  $H$ .

Therefore we suppose  $C - \langle\langle E(\tilde{D}) \cap E(C) \rangle\rangle_H$  contains an edge. This implies

$$|E(C)| - |E(D) \cap E(C)| \leq |E(C)| - 3$$

and hence by (1),

$$3 \leq |E(D) \cap E(C)| \leq |E(C)| - 3 \leq 3.$$

As all the equalities hold,  $|C| = 6$  and  $|E(D) \cap E(C)| = 3$ . Furthermore, the three edges in  $E(D) \cap E(C)$  should be adjacent, i.e., these edges determine a path in  $C$  (otherwise  $C - \langle\langle E(D) \cap E(C) \rangle\rangle_H$  is edgeless). The endvertices of this path are antipodal on  $C$  and, since each of them has positive even degree in  $D$ , their degrees in  $H$  are greater than two. This implies  $C$  is not vertex-antipodal, a contradiction.  $\blacksquare$

**Corollary 4.** *Let  $G$  be a claw-free graph in which every locally disconnected vertex is in an induced cycle of length 4 or 5, or in an induced  $EA-C_6$ . Then  $G$  has a 2-factor.*

**Proof.** If  $G$  satisfies the assumptions of the theorem, then every nonsimplicial vertex of  $G$  is 2f-eligible, hence  $\text{cl}^{2f}(G)$  is complete and  $G$  has a 2-factor by Theorem 2.  $\blacksquare$

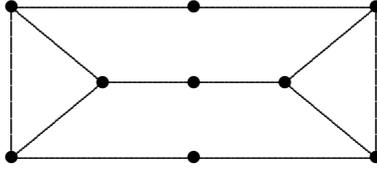


Figure 2

Consider the graph  $G$  in Figure 2. The graph  $G$  has no 2-factor, and applying local completion at any of its vertices would start a process that results in a complete graph. Each vertex of  $G$  is in some cycle of length 6, but neither of these cycles is antipodal. Hence this example shows that the antipodality condition cannot be omitted.

## 5 Concluding remarks

1. If  $x \in \text{EL}^{2f}(G) \setminus \text{EL}(G)$ , then  $x$  is in an induced cycle  $C$ , where  $C$  is a  $C_4$ , a  $C_5$  or an EA- $C_6$ , and applying local completion at  $x$  turns  $C$  into an induced cycle the length of which is one less. Eventually, all vertices in  $N_G(V(C))$  induce a clique in  $\text{cl}^{2f}(G)$ . This simple observation shows that the construction of  $\text{cl}^{2f}(G)$  can be speeded up such that, in each step when an induced  $C_4$ ,  $C_5$  or an EA- $C_6$  is identified, all vertices in  $N_G(V(C))$  are covered with a clique.

2. The 2f-closure can be slightly extended as follows. A *branch* in a graph  $G$  is a path in  $G$  with all interior vertices of degree 2 and with (distinct) endvertices of degree different from 2. The *length* of a branch is the number of its edges. If  $x \in V(G)$  is of  $d_G(x) = 2$  and  $N_G(x) = \{y_1, y_2\}$ , we say that the graph with vertex set  $V(G) \setminus \{x\}$  and edge set  $(E(G) \setminus \{xy_1, xy_2\}) \cup \{y_1y_2\}$  is obtained by *suppressing*  $x$ . The graph obtained from  $G$  by suppressing  $k - 2$  interior vertices in each branch of length  $k \geq 3$  is called the *suppression* of  $G$  and denoted  $\text{supp}(G)$ . It is easy to see that  $\text{supp}(G)$  is unique (up to isomorphism), and in  $\text{supp}(G)$  both neighbors of every vertex of degree 2 have degree different from 2. The following observation is also straightforward.

**Proposition 5.** *Let  $G$  be a graph. Then  $G$  has a 2-factor if and only if  $\text{supp}(G)$  has a 2-factor.* ■

Thus, it is possible to slightly extend the 2f-closure by setting  $\text{cl}_G^{2f}(G) = \text{cl}^{2f}(\text{supp}(G))$ . This straightforward extension allows to handle some cycles of arbitrarily large length (for example, the paths  $a_1a_2a_3a_4$  and  $b_1b_2b_3b_4$  in Figure 1 can be arbitrarily long), however, the drawback of this approach is that possibly  $|V(\text{cl}_G^{2f}(G))| \neq |V(G)|$ . We leave the technical details to the reader.

3. Combining the observations made in Remarks 1 and 2 with the approach used in [2] we can alternatively define the closure as follows. Let  $C$  be an induced cycle in  $G$  of length  $k$ , and let  $C_S$  be the corresponding cycle in  $\text{supp}(G)$ . We say that  $C$  is *2f-eligible* in  $G$  if  $k \in \{4, 5\}$ , or if  $k = 6$  and  $C$  is edge-antipodal in  $G$ , and  $C$  is *2fc-eligible* in  $G$  if  $C_S$  is 2f-eligible in  $\text{supp}(G)$ . The *local completion* of  $G$  at  $C$  is the graph  $G_C^*$  with

$V(G_C^*) = V(G)$  and  $E(G_C^*) = E(G) \cup \{uv \mid u, v \in V(C) \cup N(V(C))\}$ , and a graph  $\text{cl}_C^{2f}(G)$  is said to be a *2fc-closure of  $G$*  if there is a sequence of graphs  $G_1, \dots, G_t$  such that

- (i)  $G_1 = \text{cl}(G)$ ,
- (ii)  $G_{i+1} = \text{cl}((G_i)_{C_i}^*)$  for some 2fc-eligible cycle  $C_i$  in  $G_i$ ,  $i = 1, \dots, t-1$ ,
- (iii)  $G_t = \text{cl}_C^{2f}(G)$  contains no 2fc-eligible cycle.

The following facts are easy to see.

**Theorem 6.** *Let  $G$  be a claw-free graph. Then*

- (i) *the closure  $\text{cl}_C^{2f}(G)$  is uniquely determined,*
- (ii)  *$\text{cl}^{2f}(G) \subset \text{cl}_C^{2f}(G)$  and  $\text{cl}^{2f}(G) = \text{cl}_C^{2f}(G)$  if and only if  $G$  has no branches of length  $k \geq 3$ ,*
- (iii)  *$G$  has a 2-factor if and only if  $\text{cl}_C^{2f}(G)$  has a 2-factor.* ■

4. We show another alternative way of introducing the closure that gives a concept slightly weaker, but in some situations easier to use.

For  $x \in V(G)$  and a positive integer  $k$ , let  $N_G^k(x) = \{y \in V(G) \mid 1 \leq \text{dist}_G(x, y) \leq k\}$ , and set  $\text{EL}^k(G) = \{x \in V(G) \mid \langle N_G^k(x) \rangle_G \text{ is connected noncomplete}\}$ . The vertices in  $\text{EL}^k(G)$  will be called  *$k$ -distance-eligible* (note that  $\text{EL}^1(G) = \text{EL}(G)$ ).

For a claw-free graph  $G$ , let  $\text{cl}^{d2}(G)$  be the graph obtained from  $G$  by local completions at 2-distance-eligible vertices, as long as such a vertex exists. It is straightforward to observe that  $x \in \text{EL}^2(G)$  if and only if  $x \in V(G)$  is either eligible (i.e.  $x \in \text{EL}(G)$ ), or  $x$  is in an induced cycle of length 4 or 5. Thus, the following facts are straightforward.

**Theorem 7.** *Let  $G$  be a claw-free graph. Then*

- (i) *the closure  $\text{cl}^{d2}(G)$  is uniquely determined,*
- (ii) *there is a graph  $H$  with  $g(H) \geq 6$  such that  $L(H) = \text{cl}^{d2}(G)$ ,*
- (iii)  *$G$  has a 2-factor if and only if  $\text{cl}^{d2}(G)$  has a 2-factor.* ■

A graph  $G$  is  $N^2$ -locally connected if, for every  $x \in V(G)$ ,  $\langle N_G^2(x) \rangle_G$  is a connected graph. Clearly, if  $G$  is  $N^2$ -locally connected, then  $\text{cl}^{d2}(G)$  is a complete graph. Hence the following result by Li and Liu [7] is an immediate corollary of Theorem 7.

**Theorem G [7].** *Every  $N^2$ -locally connected claw-free graph with  $\delta(G) \geq 2$  has a 2-factor.*

The graph  $G$  in Figure 3 is an example of a graph that does not satisfy the assumptions of Theorem G, but  $\text{cl}^{d2}(G)$  is a complete graph (and hence  $G$  has a 2-factor by Theorem 7).

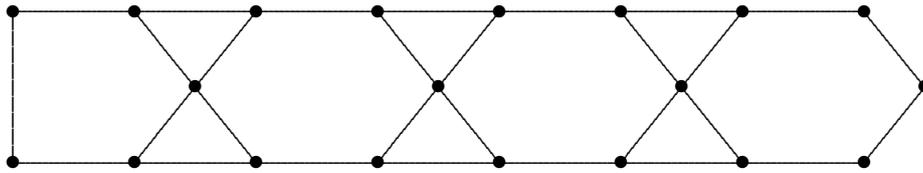


Figure 3

Consider the graph  $G$  in Figure 4. Clearly,  $G$  is claw-free and has no 2-factor. The vertex  $x$  is eligible in  $G$  (i.e.,  $x \in \text{EL}(G)$ ), hence also  $x \in \text{EL}^2(G)$ . However, applying the local completion operation to the whole distance 2-neighborhood  $N^2(x)$  would result in a graph that has a 2-factor. This example shows that modifying the 2-distance closure such that, in each step,  $N^2(x)$  of a vertex  $x \in \text{EL}^2(G)$  is covered with a clique, would result in closure that does not preserve the (non)-existence of a 2-factor.

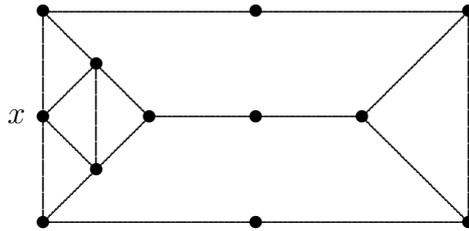


Figure 4

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